Biquaternion cryptography

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#### Outline

- KLPT in dimension 2 (joint work with Castryck, Decru, Laval, Petit and Ti) and consequences
- Orientations and Shimura class group actions (ongoing work with Castryck, Dina and Lorenzon) if time permits (but probably won't)
- Talk will focus mostly on the algebraic side and will present recent work, ongoing work and open problems
- Biquaternion algebra: tensor product of two quaternion algebras
- Over Q a biquaternion algebra is either M<sub>4</sub>(Q) or M<sub>2</sub>(B) where B is a quaternion algebra
- Many slides are "bonus slides" and are here just for completeness (i.e., don't get scared by the 31 slides)

#### Deuring correspondence

- Supersingular elliptic curves ↔ Maximal orders in B<sub>p,∞</sub> (this is usually a 2-1 correspondence)
- $\blacktriangleright \text{ Isogenies} \leftrightarrow \text{ connecting ideals}$
- $\blacktriangleright \text{ Degree of an isogeny} \leftrightarrow \text{Norm of an ideal}$
- Everything starts here with understanding the structure of Hom(E<sub>1</sub>, E<sub>2</sub>) which is a 4-dimensional Euclidean lattice of determinant p<sup>2</sup>

#### Kohel-Lauter-Petit-Tignol

- The Deuring correspondence implies that that every algorithmic problem on the elliptic curve side has a quaternion counterpart
- Isogeny pathfinding problem: Given two supersingular elliptic curves find an isogeny of degree 2<sup>k</sup> between them
- Quaternion pathfinding problem: Given two maximal orders find a connecting ideal of norm 2<sup>k</sup> between them
- KLPT2014: Quaternion pathfinding problem can be solved in polynomial time
- Many crytpographic applications but in particular it means that given a maximal order one can compute a corresponding supersingular elliptic curve

#### Brief sketch of KLPT

- Computing any connecting ideal is easy, finding a smooth norm one is the hard part
- Equivalent ideal: *I* is equivalent to *J* if *J* = *I*β for some β ∈ B<sub>p,∞</sub>
- One computes one ideal *I* of norm *N* and then tries to find an equivalent smooth norm one ↔ finding an element *z* ∈ *I* such that *N*(*z*) = *NI<sup>n</sup>*
- Ideal *I* can be generated by σ, *N*. The idea is to first solve the problem modulo *N* and then try to lift the lift the solution (this is called Strong Approximation) to an element of norm *I<sup>k</sup>*

#### Dimension 2

- What about dimension two Abelian varieties?
- The natural analogue of supersingular curves is going to be superspecial Abelian surfaces which are isomorphic to the product of two supersingular elliptic curves
- Problem 1: Only 1 superspecial surface up to isomorphism
- Solution: You have to view surfaces together with a principal polarization
- How does this translate to the algebra side?

#### Dimension 2, the algebra side

- Endomorphism rings of superspecial surfaces are maximal orders in M<sub>2</sub>(B<sub>p,∞</sub>)
- Problem 1: There is only one maximal order up to isomorphism
- Solution: You have to incorporate principal polarizations
- Ibukiyama, Katsura, Oort: Since every superspecial surface comes from a different principal polarization of E × E, one can associate a 2 × 2 matrix to every surface
- Fix E<sup>2</sup> together with the product polarization σ<sub>0</sub> and then associate a different principal polarization σ<sub>1</sub> the map σ<sub>1</sub><sup>-1</sup>σ<sub>0</sub> which is an endomorphism of E<sup>2</sup>.

#### Dimension 2, the algebra side II

This matrix is going to be quite special and actually of the following form:

$$\begin{pmatrix} s & r \\ \overline{r} & t \end{pmatrix}$$

where End(E) = O,  $r \in O$  and s, t > 0 are integers.

- This comes from the fact that M<sub>2</sub>(O) has the conjugate transpose as a totally positive involution and the above matrix will be symmetric with respect to that involution
- To get a proper correspondence we need an equivalence relation as polarizations can be composed with automorphisms
- Matrices g₁ and g₂ are equivalent if there exists u ∈ GL₂(O) such that g₂ = u\*g₁u
- How do you bring isogenies into the picture?

#### Algebraic polarized isogenies

Polarized isogenies between g<sub>1</sub>, g<sub>2</sub> will correspond to matrices γ ∈ M<sub>2</sub>(O) such that γ<sup>\*</sup>g<sub>2</sub>γ = Ng<sub>1</sub>

#### Problem

Given two matrices  $g_1, g_2$  find  $\gamma \in M_2(O)$  such that  $\gamma^* g_2 \gamma = 2^k g_1$ 

- Main result: There exists a polynomial-time algorithm for the above problem with 2<sup>k</sup> < p<sup>25</sup>
- Note that matrices g could apriori have big coefficients yet the output length of our algorithm only depends on p and not the coefficients of the g<sub>i</sub>

## Algebraic pathfinding I

• Let 
$$u = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \in M_2(O)$$
. Let  
 $\mathcal{N}(u) = N(a)N(d) + N(b)N(c) - Tr(\bar{a}b\bar{d}c)$ 

 N(u) is actually the reduced norm of u (reduced norm is multiplicative!)

► 
$$u^{-1}\mathcal{N}(u) \in M_2(O)$$

#### Lemma

Assume that  $\delta^* g_1 \delta = Nu^* g_2 u$  where  $N \in \mathbb{Z}^+$ ,  $u, \delta \in M_2(O)$ . Then there exists  $\gamma \in M_2(O)$  such that  $\gamma^* g_1 \gamma = N\mathcal{N}(u)^2 g_2$ .

 This generalizes the equivalence relation and provides more flexibility

## Algebraic pathfinding II

#### Lemma

Let 
$$g_1 = \begin{pmatrix} D & r_1 \\ \overline{r_1} & u \end{pmatrix}$$
 and  $g_2 = \begin{pmatrix} D & r_2 \\ \overline{r_2} & v \end{pmatrix}$  such that  
 $Du - N(r_1) = Dv - N(r_2)$  where  $D, u, v \in \mathbb{Z}$  and  $r_1, r_2 \in O$ .  
Then there exists  $\gamma \in M_2(O)$  such that

$$\gamma^* g_1 \gamma = D^2 g_2$$

#### Proof.

Take 
$$\gamma = \begin{pmatrix} D & r_2 - r_1 \\ 0 & D \end{pmatrix}$$

### Algebraic pathfinding III

- ▶ Goal: find u<sub>1</sub>, u<sub>2</sub> such that the top left corner of u<sub>1</sub>\*g<sub>1</sub>u<sub>1</sub> is the same as the top left corner of u<sub>2</sub>\*g<sub>2</sub>u<sub>2</sub> and is a power of 2
- ▶ Problem 1: you have to ensure that  $\mathcal{N}(u_1) = \mathcal{N}(u_2) = 2^k$
- You also need bounds on the powers of 2 that do not depend on g<sub>1</sub> and g<sub>2</sub>
- Note that this reduces the pathfinding problem to a transformation problem
- What does the top left corner look like after conjugation with u?

Algebraic pathfinding IV

• If 
$$u = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$
 and  $g = \begin{pmatrix} s & r \\ \overline{r} & t \end{pmatrix}$ , then the top left corner of  $u^*gu$  is

$$s' := s \cdot N(a) + t \cdot N(c) + \operatorname{Tr}(\bar{c}\bar{r}a)$$

- Observation 1: This does not depend on b, d!
- Observation 2: This a quadratic form in 8 variables, or one can also look at it as O<sup>2</sup> together with a quadratic module structure Q(a, c)
- Interesting fact: The determinant of this quadratic form is p<sup>4</sup> (if st - N(r) = 1, in general it is p<sup>4</sup>(st - N(r))<sup>4</sup>) so in particular it does not depend on s, t, r! Furthermore, the form is positive definite.

### Algebraic pathfinding V

- Solving Q(a, c) = A where A ∈ Z<sup>+</sup> can be done efficiently assuming some technical conditions and provided A is big enough
- Problem: Bound will depend on s, t
- ▶ Solution: Run LLL and find  $u_0$  such that the top left corner of  $u_0^* g u_0$  is smaller than  $\sqrt{p}$
- This will only ensure that s is small but using one more step one get every coefficient of the new g to be bounded
- What remains? At every step we only work with a, c and now we have to ensure that we can find a suitable b, d such that N(u) is a fixed power of 2 whose size is bounded in terms of p

#### Algebraic pathfinding VI

- Controlling the reduced norm means that given a, c we need to find b, d such that  $N(a)N(d) + N(b)N(c) Tr(\bar{a}b\bar{d}c) \text{ is a fixed power of 2.}$
- Assume that N(a) and N(c) are coprime and look at the quadratic form

$$Q(x,y) = N(a)N(y) + N(x)N(c) - Tr(\bar{a}x\bar{y}c)$$

- Instead of starting to write down Diophantine equations we stop and think about what this is algebraically
- O<sup>2</sup> can be viewed with Q as a quadratic right O-module. The submodule M<sub>1</sub> = (a, c)O is going to be the radical, i.e a submodule whose elements are orthogonal to everyone
- Goal: Try to find a right submodule  $M_2$  such that  $M_1 \oplus M_2 = O^2$

#### Algebraic pathfinding VII

- The tactic for finding M<sub>2</sub> is going to be to find a vector w that is B<sub>p,∞</sub>-independent from (a, c) and look for M<sub>2</sub> = wB<sub>p,∞</sub> ∩ O<sup>2</sup>.
- ► For every such choice M<sub>2</sub> is a right O-module whose intersection with M<sub>1</sub> is trivial, however there is only one choice to ensure that M<sub>1</sub> and M<sub>2</sub> generate O<sup>2</sup>
- Let  $\alpha, \beta$  be such that  $\alpha N(a) + \beta N(c) = 1$
- w = (βN(c)a, -αN(a)c) is going to be an appropriate choice (it is enough to show that together with (a, c) they generate (1,0) and (0,1))

#### Algebraic pathfinding VIII

- What is M<sub>2</sub>? Use the duck method (if it quacks like a duck, waddles like a duck, then it has to be a duck)!
- *M*<sub>2</sub> is going to be an invertible right *O*-module (i.e., locally free of rank 1)
- It has two elements of coprime norm , namely (βN(c), −αcā), (βac̄, −αN(a)) ∈ M<sub>2</sub> which actually generate it
- lt has to be a  $Hom(E, E_1)$
- Actually one has the following formula:

$$Q((\beta N(c), -\alpha c\bar{a})o_1 + (\beta a\bar{c}, -\alpha N(a))o_2) = 1/N(c)N(N(c)o_1 + a\bar{c}o_2).$$

This formula actually gives a module isomorphism between M<sub>2</sub> and the right ideal generated by N(c) and ac̄ which is a N(c) homothethy between quadratic modules. Why do we care about this?

### Algebraic pathfinding IX

- The above formula tells me that if I find an element of norm N(c)N in the ideal generated by N(c) and ac̄ (an ideal of norm N(c)), then I find an element of norm N in M<sub>2</sub>
- Hence I onleed need to find an element of norm N(c)2<sup>k</sup> in the aforementioned ideal. But how do I do that? Use 1-dim KLPT!
- Since we use O as the nicest maximal order possible KLPT will give as a power of 2 smaller than p<sup>3</sup>
- The terrible bound comes from the reduction step and solving the previous norm equation

#### Potential improvements

Let's get back to the quadratic form

$$s \cdot N(a) + t \cdot N(c) + \operatorname{Tr}(\bar{c}\bar{r}a)$$

This is again O<sup>2</sup> with a quadratic module structure

- Would be great to find an equivalent matrix where s, t are small (right now we move out of the equivalence class)
- Even nicer would be to solve

$$s \cdot N(a) + t \cdot N(c) + \operatorname{Tr}(\bar{c}\bar{r}a) = I^k$$

directly where the bound does not depend on s, t

## Applications

- Efficient endomorphism ring to surface translation (2-dim ideal to isogeny algorithm)
- Breaking 2-dimensional generalizations of the CGL hash function without trusted setup
- This break involves an isogeny to matrix algorithm which requires solving solving a principal ideal problem in left ideals of M<sub>2</sub>(O)
- For a chain of (1, 1)-isogenies this can be avoided by using a polynomial-time precomputation computing γ matrices for every possible rank 2 kernel (note that in dimension 2, every surface is just E<sup>2</sup> with a different principal polarization)
- Alternatively one can also solve it using algorithms for the principal ideal problem

#### Speculations on 2-dimensional SQIsign

- KLPT<sup>2</sup> naturally avoids going through a special surface (conjecturally) so SQIsign can be built from it but problems arise
- Paths are too long, so it is not yet clear how to make it practical (very interesting open problem!)
- ZK knowledge assumption needs to be studied
- What about generalizations of SQIsignHD?

#### Speculations on 2-dimensional SQIsign

- Non-smooth degree matrices can be returned which are much smaller but they go through a special surface
- ► In theory a (reduced) degree ≈ p isogeny should be possible but finding it is not obvious
- Polarized isogenies do not form a lattice, so one can't find the shortest polarized isogeny with lattice reduction
- Interesting to pursue this direction as well as endomorphism ring computation in dimension 2 has O(p) complexity (by recent survey from Anni, Bisson, Garcia, lezzi, Wesolowski citing Costello-Smith algorithm)

#### Alternative description of IKO

- IKO paradigm does not seem like the natural generalization of the Deuring correspondence
- One way is to look at totally positive involutions on M<sub>2</sub>(O)
- Another more natural way is to look at maximal orders together with a totally positive involution (here isogenies will correspond to certain kind of conjugations)
- One can algorithmically navigate between them using the principal ideal problem

### Endomorphism ring problems

- Given a surface find a basis of the endomorphism ring
- Given a surface find the corresponding g matrix
- Algorithmically equivalent:
- ▶ one finds an isomorphism between the endomorphism algebra and M<sub>2</sub>(B<sub>p,∞</sub>)
- Explicit conjugation to M<sub>2</sub>(O) using the principal ideal problem
- The g matrix can be read of from the Rosati involution using linear algebra

#### Group actions

- What other things are possible with biquaternions?
- One can generalize class group actions to dimension 2 but one has to account for polarizations
- One can view every maximal order as M<sub>2</sub>(O) (where End(E) ≅ O) together with the Rosati involution given by σ(x) = g<sup>-1</sup>x<sup>T</sup>g
- Instead of the class group one can use the Shimura class group of CM orders

#### Orientations

- Shimura class group actions are in characteristic 0 and they generalize easily to ordinary abelian surfaces. What can we do with superspecial surfaces?
- Orientations are **NOT** just an embedding of a CM order in the endomorphism ring
- Take the endomorphism ring together with the involution. An orientation is a CM order in the endomorphism ring where the involution σ acts as complex conjugation
- Simply put: one has Z[a, b] as a subring where a is real and σ(a) = a and ab = ba

# Ongoing work

- We can create orientations and show that these group actions are free
- Orbits are very interesting and depend on something called CM types which you don't really see in postive characteristic
- One can efficiently compute them á la SCALLOP-HD
- Many open problems still arise

#### Conclusion

- Biquaternion cryptography poses many open questions
- Does everything we know from the quaternion world generalize to higher dimensions?
- Will there be applications that will outperform 1-dimensional counterparts (e.g., a recent 3-dimensional hash function significantly outperforms CGL)

#### **Orientations II**

- Find a symmetric element a
- Compute the centralizer of a in M<sub>2</sub>(B<sub>p,∞</sub>) which will be the quaternion algebra Q(a) ⊗ B<sub>p,∞</sub> by the double centralizer theorem
- If one intersects it with the original maximal order, one can prove that σ will act as quaternion conjugation on this quaternion algebra (σ will be a standard involution)
- Just take a quadratic order

#### **Orientations III**

- Through lifting to characteristic 0, this will provide a free and transitive group action
- One still has to translate the orientation
- This can be done through interpolation data (like SCALLOP-HD)
- Drawback: one needs 8-dimensional isogenies

#### **Orientations III**

- Gives rise to an order embedding problem which can be solved in the smallish cases using lattice reduction details on the board
- ► Frobenius is not great as it does not generate a CM order almost always. There is a group action of the class group of Z[√-p] which still provides interesting questions
- Several open questions in terms of security and efficiency