

Practical Effective Class Group Action using 4-Dimensional Isogenies

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Introduction: class group action on oriented curves

Orientations

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- Let E/\mathbb{F}_{p^2} be a supersingular elliptic curve. A (primitive) \mathfrak{O} -orientation of E is an embedding:

$$\iota : \mathfrak{O} \hookrightarrow \text{End}(E)$$

that is maximal (it does not extend to a superorder of \mathfrak{O}).

- We say that (E, ι) is \mathfrak{O} -oriented.

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- An ideal $\mathfrak{a} \subseteq \mathfrak{D}$ corresponds to an isogeny $\varphi_{\mathfrak{a}} : E \rightarrow E_{\mathfrak{a}}$ of kernel:

$$E[\mathfrak{a}] := \{P \in E \mid \forall \alpha \in \mathfrak{a}, \quad \iota(\alpha)(P) = 0\}$$

- There is also an \mathfrak{D} -orientation

$$\iota_{\mathfrak{a}} := (\varphi_{\mathfrak{a}})_*(\iota) : \alpha \mapsto \frac{1}{N(\mathfrak{a})} \varphi_{\mathfrak{a}} \circ \iota(\alpha) \circ \hat{\varphi}_{\mathfrak{a}}$$

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on $E_{\mathfrak{a}}$.

- The action is trivial $(E, \iota) \simeq (E_{\mathfrak{a}}, \iota_{\mathfrak{a}})$ if and only if \mathfrak{a} is principal.

Example: CSIDH and CSURF

- Let $p \equiv 7 \pmod{8}$. Consider a supersingular Montgomery curve

$$E : y^2 = x^3 + Ax^2 + x$$

with $A \in \mathbb{F}_p$.

- Then $\text{End}_{\mathbb{F}_p}(E)$ contains the Frobenius endomorphism

$$\pi_p : (x, y) \in E \longmapsto (x^p, y^p) \in E,$$

which satisfies $\pi_p^2 = -[p]$.

- Hence E is $\mathbb{Z}[\sqrt{-p}]$ -oriented:

$$\begin{array}{ccc} \mathbb{Z}[\sqrt{-p}] & \hookrightarrow & \text{End}_{\mathbb{F}_p}(E) \\ \sqrt{-p} & \longmapsto & \pi_p \end{array} .$$

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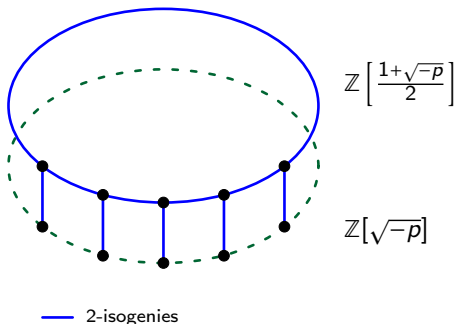
$$\begin{array}{ccc} \mathbb{Z}[\sqrt{-p}] & \hookrightarrow & \text{End}_{\mathbb{F}_p}(E) \\ \sqrt{-p} & \mapsto & \pi_p \end{array}.$$

- This orientation is not always primitive: there are two cases.

Example: CSIDH and CSURF

E is either:

- On the surface: primitively $\mathbb{Z}[(1 + \sqrt{-p})/2]$ -oriented (CSURF).
- On the floor: primitively $\mathbb{Z}[\sqrt{-p}]$ -oriented (CSIDH).



Effective group action

Definition

An *effective group action* (EGA) $G \curvearrowright X$ is:

- 1 Commutative.
- 2 Free: $\forall x \in X, g \in G, \quad g \cdot x = x \implies g = e.$
- 3 Transitive: $\forall x, y \in X, \exists g \in G, \quad g \cdot x = y.$
- 4 Easy to compute: $g \cdot x$ can be evaluated in polynomial time for all $g \in G$ and $x \in X.$
- 5 One way: given x and $g \cdot x$, $g \in G$ is hard to find.

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- With effective group actions, we can derive many schemes (including key exchange, signatures and more).

Restricted effective group actions


- Actually, group actions based on orientations are restricted effective group actions. We can act by ideals of small norms $\mathfrak{l}_1, \dots, \mathfrak{l}_t$ that generate $\text{Cl}(\mathfrak{O})$.
- To act with the whole of $\text{Cl}(\mathfrak{O})$ we consider products

$$\mathfrak{a} = \prod_{i=1}^t \mathfrak{l}_i^{e_i}.$$

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- To act with the whole of $\text{Cl}(\mathfrak{O})$ we consider products

$$\mathfrak{a} = \prod_{i=1}^t \mathfrak{l}_i^{e_i}.$$

-  **Issue:** it is non trivial (and not very efficient) to sample uniform classes in $\text{Cl}(\mathfrak{O})$ with such products, as required in some protocols (e.g. CSI-FiSh).

The Clapoti method

d -isogenies and the dual isogeny in higher dimension

Definition (d -isogeny)

Let $\varphi : (A, \lambda_A) \rightarrow (B, \lambda_B)$ be an isogeny between two principally polarized abelian varieties (PPAV). We define:

- $\tilde{\varphi} := \lambda_A^{-1} \circ \hat{\varphi} \circ \lambda_B : B \rightarrow A$.

$$B \xrightarrow{\lambda_B} \hat{B} \xrightarrow{\hat{\varphi}} \hat{A} \xrightarrow{\lambda_A^{-1}} A$$

- We say that φ is a d -isogeny or has polarized degree d if $\tilde{\varphi} \circ \varphi = [d]_A$.

Kani's embedding lemma [Kan97]

Definition (isogeny diamond)

An (a, b) -isogeny diamond is a commutative diagram s.t.:

$$\begin{array}{ccc} A' & \xrightarrow{\varphi'} & B' \\ \psi \uparrow & & \uparrow \psi' \\ A & \xrightarrow{\varphi} & B \end{array}$$

where φ, φ' are a -isogenies and ψ, ψ' are b -isogenies.

Lemma (Kani)

Consider the (a, b) -isogeny diamond on the left. Then:

- $F : A \times B' \longrightarrow B \times A',$

$$F := \begin{pmatrix} \varphi & \widetilde{\psi'} \\ -\psi & \widetilde{\varphi'} \end{pmatrix}$$

is a d -isogeny with $d = a + b$.

- If $a \wedge b = 1$, then

$$\ker(F) = \{(\widetilde{\varphi}(x), \psi'(x)) \mid x \in B[d]\}.$$

Computing 2^e -isogenies

Theorem (D. and Robert)

Let k be a field such that $\text{char}(k) \neq 2$. Then there exists an algorithm that takes as input:

- A principally polarised abelian variety A of dimension g defined over k ;
- Points $T_1, \dots, T_g \in A[2^{e+2}]$ defined over k forming a maximal isotropic subgroup of $A[2^{e+2}]$;

And returns a 2^e -isogeny $F : A \rightarrow B$ with kernel $\langle [4]T_1, \dots, [4]T_g \rangle$ represented as a chain of 2-isogenies with a number of operations over k polynomial in e and 2^g .

The Clapoti method

Goal: Compute E_a for any $a \in \mathfrak{D}$.

Assumption: $p = c2^e - 1$.

- We solve:

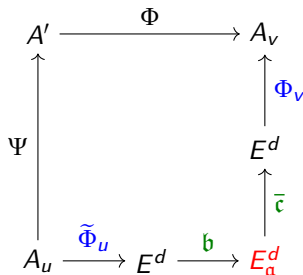
$$uN(b) + vN(c) = 2^f,$$

with $b, c \sim a$, $f \leq e - 2$ and $\gcd(uN(b), vN(c)) = 1$.

- If Φ_u and Φ_v are d -dimensional, the resulting Kani 2^f -isogeny

$$F : A_u \times A_v \longrightarrow E_a^d \times A'$$

is $2d$ -dimensional.



The Clapoti method - Outline

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Step 1: Find ideals $\mathfrak{b}, \mathfrak{c} \sim \mathfrak{a}$ and $u, v \in \mathbb{N}$ such that $\gcd(uN(\mathfrak{b}), vN(\mathfrak{c})) = 1$ and

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Step 4: Compute a $2d$ -dimensional isogeny $F : A_v \times A_v \rightarrow E_{\mathfrak{a}}^d \times A'$ embedding $\varphi_{\mathfrak{b}}, \varphi_{\mathfrak{c}}, \Phi_u, \Phi_v$.

Step 5: Extract $E_{\mathfrak{a}}$ from the codomain $E_{\mathfrak{a}}^d \times A'$.

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- In KlaPoTi [PPS24], they impose $u = v = 1$:

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- KLPT [KLPT14] is used to find $\mathfrak{b}, \mathfrak{c} \sim \mathfrak{a}$.
- Only possible for small discriminants $|\text{disc}(\mathfrak{O})| \leq 2^{f/3} \simeq p^{1/3}$.

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- Only possible for small discriminants $|\text{disc}(\mathfrak{O})| \leq 2^{f/3} \simeq p^{1/3}$.
- PEGASIS: a solution for $|\text{disc}(\mathfrak{O})| \simeq p$ but with $d = 2$.
- We have to compute 4-dimensional isogenies!

From Clapoti to Pegasus: making it effective and efficient

Step 2: computing Φ_u and Φ_v - sums of squares

Goal: Given $u < 2^{e-2}$ odd and an \mathfrak{D} -oriented curve (E, ι) , compute a u -isogeny $\Phi_u : E^2 \rightarrow A_u$.

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Issue: With any u , it requires to compute a 4-dimensional isogeny [NO23].

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Idea: Require u of special form.

- Assume $u = g_u(x_u^2 + y_u^2)$.

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- Then, we can define: We can define

$$\Phi_u := \begin{pmatrix} x_u & -y_u \\ y_u & x_u \end{pmatrix} \begin{pmatrix} \varphi_u & 0 \\ 0 & \varphi_u \end{pmatrix}: E^2 \rightarrow E_u^2$$

with $\deg(\varphi_u) = g_u$.

- g_u is a product of small primes that split in \mathfrak{D} so that φ_u is given by an ideal action g_u .
- Only 1-dimensional computations are involved.

Step 1: tweaking the norm equation

- We want to solve:

$$uN(\mathfrak{b}) + vN(\mathfrak{c}) = 2^f$$

with $\mathfrak{b}, \mathfrak{c} \sim \mathfrak{a}$, $\gcd(uN(\mathfrak{b}), vN(\mathfrak{c})) = 1$, $f \leq e - 2$,

$$u = g_u(x_u^2 + y_u^2) \quad \text{and} \quad v = g_v(x_v^2 + y_v^2).$$

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- **Issue:** This might be too tight to be solved.
- **Solution:** Let $\mathfrak{b} = \mathfrak{b}_1 \cdot \mathfrak{b}_2$ and $\mathfrak{c} = \mathfrak{c}_1 \cdot \mathfrak{c}_2$, where \mathfrak{b}_1 and \mathfrak{c}_1 are a product of small prime ideals in \mathfrak{O} .
- Solve the following instead:

$$uN(\mathfrak{b}_2) + vN(\mathfrak{c}_2) = 2^f.$$

Step 1: an algorithm

Goal: solve $uN(\mathfrak{b}_2) + vN(\mathfrak{c}_2) = 2^f$.

- Sample $\beta, \gamma \in \mathfrak{a}$ as follows:
 - Find a Lagrange-Gauss reduced basis (α_1, α_2) of \mathfrak{a} .
 - Sample small $x, y, z, t \in \mathbb{Z}$ and set $\beta := x\alpha_1 + y\alpha_2$ and $\gamma := z\alpha_1 + t\alpha_2$.
- Set $\mathfrak{b} := \alpha\bar{\beta}/N(\mathfrak{a})$ and $\mathfrak{c} := \alpha\bar{\gamma}/N(\mathfrak{a})$.
- Factor $\mathfrak{b} = \mathfrak{b}_1 \cdot \mathfrak{b}_2$ and $\mathfrak{c} = \mathfrak{c}_1 \cdot \mathfrak{c}_2$.
- Repeat until we can find suitable u, v .

Step 1: norm constraints

- By Minkowski's bounds, the Lagrange-Gauss reduced basis satisfies:

$$N(\alpha_1)N(\alpha_2) \simeq N(\mathfrak{a})^2|\Delta|$$

- So we expect $N(\alpha_1) \simeq N(\alpha_2) \simeq N(\mathfrak{a})\sqrt{|\Delta|}$, so that $N(\beta) \simeq N(\gamma) \simeq N(\mathfrak{a})\sqrt{|\Delta|}$ and:

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- To solve $uN(\mathfrak{b}_2) + vN(\mathfrak{c}_2) = 2^f$, we need $N(\mathfrak{b}_2)N(\mathfrak{c}_2) \leq 2^f \simeq p$.
- We can solve it as long as $|\Delta| \leq p$.
- **Example:** In CSURF, $|\Delta| = p$.

Steps 3-5: applying Kani's lemma

- We have the following $(uN(\mathfrak{b}_2), vN(\mathfrak{c}_2))$ -isogeny diamond:

$$\begin{array}{ccccc}
 E'^2 & \xrightarrow{\Phi} & E_v^2 & & \\
 \uparrow \Psi & & \uparrow \Phi_v & & \\
 & & E_{c_1}^2 & \xleftarrow{c_1} & E^2 \\
 & & \uparrow \bar{c}_2 & & \\
 E_u^2 & \xrightarrow{\tilde{\Phi}_u} & E_{b_1}^2 & \xrightarrow{b_2} & E_a^2 \\
 & & \uparrow b_1 & & \\
 & & E^2 & &
 \end{array}$$

Steps 3-5: applying Kani's lemma

- This isogeny diamond yields a 2^f -isogeny 4-dimensional

$$F = \begin{pmatrix} \Phi_{b_2} \circ \tilde{\Phi}_u & \Phi_{c_2} \circ \tilde{\Phi}_v \\ -\Psi & \tilde{\Phi} \end{pmatrix} : E_u^2 \times E_v^2 \longrightarrow E_a^2 \times E'^2.$$

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- The 2^{f+2} torsion above $\ker(F)$ can be computed by evaluating Φ_u , Φ_v and:

$$\hat{\varphi}_{c_2} \circ \varphi_{b_2} = \frac{1}{N(b_1)N(c_1)} \varphi_{c_1} \circ \iota \left(\frac{\bar{\beta}\gamma}{N(a)} \right) \circ \hat{\varphi}_{b_1}$$

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- F can then be computed efficiently with theta coordinates [Dar24].
- We can then extract E_a from the codomain $E_a^2 \times E'^2$.
- The orientation $\iota_a := (\varphi_a)_* \iota$ on E_a can be evaluated with F (unnecessary for CSURF).

Implementation for CSURF

Parameter set	Step 1 (s)	Step 2-3 (s)	Steps 4-5 (s)	Total (s)
500	0.097	0.477	0.960	1.534
1000	0.212	1.159	2.838	4.210
1500	1.186	2.853	6.491	10.530
2000	1.675	8.337	11.327	21.339
4000	15.606	52.808	53.463	121.876

Table: SageMath 10.5 timings in sec on Intel Core i5-1235U. Step 1 is the time to solve the norm equation, Steps 2-3 the time to compute all required 1-dimensional isogenies, and Steps 4-5 the time to compute the 4-dimensional isogeny.

Comparison with state of the art

Paper	Impl.		500	1000	1500	2000	4000
SCALLOP [FFK+23]*	C++		35s	12m30s	–	–	–
SCALLOP-HD [CLP24]*	Sage		88s	19m	–	–	–
PEARL-SCALLOP [ABE+24]	C++		30s	58s	12m	–	–
KLaPoTi [PPS24]	Sage		200s	–	–	–	–
	Rust		1.95s	–	–	–	–
PEGASIS (This work)	Sage		1.53s	4.21s	10.5s	21.3s	2m2s

Table: Comparison between PEGASIS and other effective group actions in the literature. The last 5 columns gives the timings corresponding to the different security levels, where s/m gives the number of seconds/minutes in wall-clock time. SCALLOP and SCALLOP-HD are starred because they were measured on a different hardware setup.

Conclusion

To sum up:

- We now have an unrestricted group action which is efficient in practice.
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Future works/open questions:

- Need to implement 4-dimensional isogenies in C and/or Rust.
- CSURF was efficient because computations were done over \mathbb{F}_p . Need to better understand 4-dimensional isogeny computations over \mathbb{F}_p .
- Could we do better in dimension 2?
- What can be done when $|\text{disc}(\mathfrak{D})| \gg p$?

Thanks for listening!



P. Dartois, J. Komada Eriksen, T. B. Fouotsa, A. Herlédan Le Merdy, R. Invernizzi, D. Robert, R. Rueger, F. Vercauteren and B. Wesolowski. PEGASIS: Practical Effective Class Group Action using 4-Dimensional Isogenies. e-Print <https://eprint.iacr.org/2023/436>

Further algorithmic details

Step 2: computing Φ_u and Φ_v - general case

Goal: Given $u < 2^{e-2}$ odd and an \mathfrak{D} -oriented curve (E, ι) , compute a u -isogeny $\Phi_u : E^2 \rightarrow A_u$.

- A method inspired from QFESTA [NO23].

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Goal: Given $u < 2^{e-2}$ odd and an \mathfrak{O} -oriented curve (E, ι) , compute a u -isogeny $\Phi_u : E^2 \rightarrow A_u$.

- A method inspired from QFESTA [NO23].
- Let $\Delta := \text{disc}(\mathfrak{O})$ and assume $u(2^f - u) := \Omega(|\Delta| \log(|\Delta|))$ (with $f \leq e - 2$).
- Solve:

$$x^2 + z^2 + |\Delta|(y^2 + t^2) = u(2^f - u),$$

with $x, y, z, t \in \mathbb{Z}$.

Step 2: computing Φ_u and Φ_v - general case

Goal: Given $u < 2^{e-2}$ odd and an \mathfrak{D} -oriented curve (E, ι) , compute a u -isogeny $\Phi_u : E^2 \rightarrow A_u$.

- A method inspired from QFESTA [NO23].
- Let $\Delta := \text{disc}(\mathfrak{D})$ and assume $u(2^f - u) := \Omega(|\Delta| \log(|\Delta|))$ (with $f \leq e - 2$).

- Solve:

$$x^2 + z^2 + |\Delta|(y^2 + t^2) = u(2^f - u),$$

with $x, y, z, t \in \mathbb{Z}$.

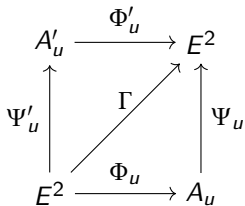
- Let $\gamma_1 := x + \sqrt{\Delta}y, \gamma_2 := z + \sqrt{\Delta}t \in \mathfrak{D}$ and:

$$\Gamma := \begin{pmatrix} \iota(\gamma_1) & \iota(\overline{\gamma_2}) \\ -\iota(\gamma_2) & \iota(\overline{\gamma_1}) \end{pmatrix} \in \text{End}(E^2).$$

- Then $\tilde{\Gamma} \circ \Gamma := [N(\gamma_1) + N(\gamma_2)] = u(2^f - u)$.

Step 2: computing Φ_u and Φ_v - general case

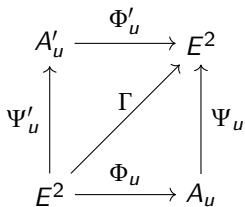
- Consider the isogeny diamond:



with $\deg(\Phi_u) = u$ and
 $\deg(\Psi_u) = 2^f - u$.

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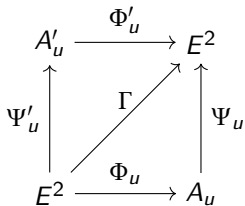
with $\deg(\Phi_u) = u$ and $\deg(\Psi_u) = 2^f - u$.

- By Kani's lemma, it induces a 2^f -isogeny

$$F_u := \begin{pmatrix} \Phi_u & \widetilde{\Psi}_u \\ -\Psi'_u & \widetilde{\Phi}'_u \end{pmatrix} : E^2 \longrightarrow A_u \times A'_u,$$

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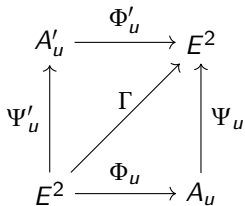
- With kernel:

$$\ker(F_u) = \{([u]P, [u]Q, \Gamma(P, Q)) \mid P, Q \in E[2^f]\}.$$

- Knowing ι , we can compute 2^{f+2} -torsion above $\ker(F_u)$ and F_u .

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- F_u represents Φ_u .

Step 1: rerandomization

Issue: What happens when $N(\alpha_1) \ll N(\alpha_2)$?

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Solution:

- Replace α by $\iota\alpha$ for a small prime ideal ι .
- Replace E by E_{ι} .
- Repeat until $N(\alpha_1) \simeq N(\alpha_2)$ (for the new ideal α).